



A quick survey of h-Principle and isometric embeddings

Roberto De Leo
Department of Mathematics



Plan of the presentation:

- General results about isometric immersions



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- The Nash-Gromov Implicit Function Theorem



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- General results about isometric immersions
- The Nash-Gromov Implicit Function Theorem
- Inducing structures on manifolds



Main Sources

- D. Spring, "The golden age of immersion theory in topology: 1959-1973", <http://arxiv.org/abs/math/0307127> (2003)
- M. Gromov, V. Rokhlin, "Embeddings and immersions in Riemannian geometry", *Russian Mathematical Surveys*, 25:5 (1970)
- M. Gromov, "Partial Differential Relations", Springer, 1983
- M. Gromov, "Geometric, Algebraic and Analytic Descendants of Nash Isometric Embedding Theorems", 2015, <http://www.ihes.fr/~gromov/PDF/nash-copy-Oct9.pdf>
- R. De Leo, "A note on non-free isometric immersions", *Russian Math Surveys*, 63:3 (2010)
- G. D'Ambra, R. De Leo, A. Loi, "Partially isometric immersions and free maps", *Geometriae Dedicata*, 151:1 (2011)
- R. De Leo, "On some geometrical and analytical problems arising from the theory of Isometric Immersion", 2011,



Isometric Embeddings



The isometric immersions problem

Question. Given a C^k Riemannian metric $g = g_{\alpha\beta}(x) dx^\alpha \otimes dx^\beta$ on M^n , for which q and k' can we find a (global or local) $C^{k'}$ isometric immersion $f : M \rightarrow \mathbb{R}^q$?



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Namely, can we find q (global or local) functions $f^a \in C^{k'}(M)$ such that

$$\delta_{ab} \partial_\alpha f^a(x) \partial_\beta f^b(x) = g_{\alpha\beta}(x)?$$



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Remark: for $n = 2$ and $q = 3$, we can rearrange the coordinates so that $f(x, y, z) = (x, y, z(x, y))$ and the equation above is equivalent to the following Monge-Ampère type eq., known as Darboux equation:

$$\det(\nabla_\alpha(\nabla_\beta z)) = K(\det g)(1 - \|\text{grad}(z)\|^2)$$



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It turns out that the answer depends on the regularity.



Local results: Analytical case

C^{an} -Local Conjecture (Schläfli (1873)¹)

Every 2-dimensional analytical Riemannian manifold admits analytical local isometric embeddings into \mathbb{R}^3 .

¹ L. Schaeffli, "Nota alla memoria del Sig. Beltrami sugli spazi di curvatura costante", Ann. di Mat., 5 (1873), 170-193

³ M. Janet, "Sur la possibilité de plonger un espace Riemannien donné dans une espace Euclidéen", Annal. Soc. Polon. Math., 5 (1926), 38-43

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C^{an} -Local Theorem (Janet (1926)², Cartan (1927)³)

Every n -dimensional analytical Riemannian manifold admits analytical local isometric embedding into \mathbb{R}^{s_n} , $s_n = n(n+1)/2$.

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Local results: Smooth case

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Every 2-dimensional analytical Riemannian manifold admits smooth local isometric embeddings into \mathbb{R}^3 .



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This problem is still open, e.g. see:

- Yau, "Problem Section, Seminar on Diff. Geom.", Ann. of Math. Studies 102, Princeton University Press (1982)
- Lin, "The local isometric embedding in \mathbb{R}^3 of 2-dim. Riem. mfd's with non-neg. curv", J. of Diff. Geom. 21 (1985), 213-230
- Hong, Zuily, "Existence of C^∞ local solutions for the Monge-Ampère equation", Inv. Math. 89 (1987), 645-661
- Han, Hong, "Isometric Embedding of Riemannian Manifolds in Euclidean Spaces", 2006, Math. Surv. and Monographs, AMS
- Han, "Isometric Embeddings of Surfaces in \mathbb{R}^3 ", Recent Developments in Geometry and Analysis (2012), 113-145



Local results: General case

The following are corollary of global results of Nash and Kuiper that we are going to present shortly:

Theorem (Nash (1954), Kuiper (1955))

Every C^1 Riemannian n -manifold admits C^1 local isometric immersions into \mathbb{R}^{n+1} .



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Theorem (Nash (1956))

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Remark 1: the case $r = 2$ is still open.



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Remark 1: the case $r = 2$ is still open.

Remark 2: Gromov improved the second result to $q = n^2 + 10n + 3$ for $r = 3$ and $q = s_{n+2}$ for $r \geq 4$.



Local results: General case

Conjecture (Gromov (2015))

Every C^r parallelizable Riemannian n -manifold admits C^r local isometric immersions into \mathbb{R}^q for $q = s_n + 1$ and $r = 1, 2, \dots, \infty, \text{an}$.



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Conjecture (Gromov (2015))

Let f be a global analytical section of the bundle $\mathcal{F}(M)$ of frames over the parallelizable n -manifold M . Then there exists $f \in C^{\text{an}}(M, \mathbb{R}^{s_n+1})$ such that $f_ f$ is an orthonormal $(s_n + 1)$ -frame in \mathbb{R}^{s_n+1} .*



Global results

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Let g be a C^r Riemannian metric on M^n , $r = 3, 4, \dots, \infty$. Then there exist C^r isometries of (M, g) into \mathbb{R}^q for $q = 3s_n + 4n$ if M is compact and into $q = (n + 1)(3s_n + 4n)$ if M is open.



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C^{an} Theorem (Nash (1954))

Let g be a C^{an} Riemannian metric on M^n . Then there exist C^{an} isometries $f : (M, g) \rightarrow \mathbb{R}^q$ for $q = 3s_n + 4n$.



Open Problems and Conjectures

Question

Do there exist C^{an} or C^∞ Riemannian n -manifolds admitting C^r isometric immersions into \mathbb{R}^q for some q_r but no C^{an} or C^∞ isometric immersions for $q \leq (1 + c_r)q_r$ for some $c_r > 0$?



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Conjecture

If $q > 0.36n^2 + 1.36n$, all C^2 Riemannian n -manifolds admit global isometric C^2 immersions into \mathbb{R}^q



The Nash-Gromov Implicit Function Theorem



Partial Differential Operators

Let $F \xrightarrow{\pi_F} E$ a C^∞ -fibration and $G \xrightarrow{\pi_G} E$ a vector bundle.
Let $\Gamma^r F$ the C^r sections of $F \xrightarrow{\pi_F} E$ and similarly for $\Gamma^0 G$.



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Definition

A C^k PDO over F of order r with values in G is a map

$$\mathcal{L}_r : \Gamma^r F \rightarrow \Gamma^0 G$$

whose coeffs, in any coord system, are all C^k and whose value on a section $f \in \Gamma^r F$ at a point $x \in E$ depends only on $j_x^r f$.



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In coordinates (x^α, f^i) and (x^α, g^a) , \mathcal{L}_r writes as

$$\mathcal{L}_r(f)(x^\alpha) = (\Lambda_r^a(x^\alpha, f^i(x^\alpha), \partial_\alpha f^i(x^\alpha), \dots, \partial_{\alpha_1 \dots \alpha_r} f^i(x^\alpha))).$$

where $\Lambda_r = (\Lambda_r^a) : J^r F \rightarrow G$ is some C^k map.



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The equation

$$\mathcal{L}_r(f) = \phi$$

is then equivalent to

$$\Lambda_r^a(x^\alpha, f^i(x^\alpha), \partial f_\alpha^i(x^\alpha), \dots, \partial f_{\alpha_1 \dots \alpha_r}^i(x^\alpha)) = \phi^a(x^\alpha)$$



Partial Differential Operators

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The corresponding map $\Lambda_\xi : J^1(M, \mathbb{R}) \rightarrow M \times \mathbb{R}$ is defined as

$$\Lambda_\xi(x^\alpha, f, f_\alpha) = \xi^\alpha(x) f_\alpha.$$



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The corresponding PDE

$$(j^1 f)^* \Lambda_\xi = \phi$$

is called *cohomological equation*. In coordinates writes as

$$\xi^\alpha(x) \partial_\alpha f(x) = \phi(x)$$



Partial Differential Operators

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Consider $F = M \times \mathbb{R}^q$ and $G = S_2^0 M$, so that $J^r(F) = J^r(M, \mathbb{R}^q)$.



Partial Differential Operators

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Consider $F = M \times \mathbb{R}^q$ and $G = S_2^0 M$, so that $J^r(F) = J^r(M, \mathbb{R}^q)$. The pull-back operator

$$\mathcal{D}_{M,q} : C^1(M, \mathbb{R}^q) \simeq \Gamma^1 F \rightarrow \Gamma^0(S_2^0 M)$$

defined as $\mathcal{D}_{M,q}(f) = f^* e_q$ is also a PDO of order 1.



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In coordinates

$$\mathcal{D}_{M,q}(f) = \delta_{ij} \partial_\alpha f^i \partial_\beta f^j,$$

so that the corresponding map $\Lambda_{M,q} : J^1(M, \mathbb{R}^q) \rightarrow S_2^0 M$ is defined as

$$\Lambda_{M,q}(x^\alpha, f, f_\alpha) = \delta_{ij} f_\alpha^i f_\beta^j.$$



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Indeed take a C^1 curve $f_t \in \Gamma^r F$ with $f_0 = f$ and let $\eta_f(x_0) = df_t(x_0)/dt|_{t=0}$.



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The set $\Gamma_f^r = \Gamma^r(f^*(VF))$ of C^r sections of $VF = \ker \pi_F$ can be thought as the tangent space at f of $\Gamma^r F$.

Indeed take a C^1 curve $f_t \in \Gamma^r F$ with $f_0 = f$ and let $\eta_f(x_0) = df_t(x_0)/dt|_{t=0}$. Then

$$\begin{aligned} T_{x_0} \pi_F(\eta_f(x_0)) &= T_{x_0} \pi_F \left(\left. \frac{df_t(x_0)}{dt} \right|_{t=0} \right) = \\ &= \left. \frac{d(\pi_F \circ f_t)(x_0)}{dt} \right|_{t=0} = \left. \frac{dx_0}{dt} \right|_{t=0} = 0, \end{aligned}$$

namely $\eta_f \in \Gamma_f^r$.



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The *linearization* of \mathcal{L}_r at f is the *linear* PDO

$$\ell_{r,f} : \Gamma_f^r \rightarrow \Gamma^0 G$$

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The PDO

$$\ell_r : \Gamma^r(VF) \rightarrow \Gamma^0 G,$$

defined as $\ell_r(f, \eta) = \ell_{r,f}(\eta)$, is the *tangent map* (or *differential*) of \mathcal{L}_r .



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Example

The Lie derivative L_ξ is linear and so it is to be expected that its differential l_ξ is identical to it. Indeed

$$l_\xi(f, \delta f) = \delta L_\xi(f) = \delta(\xi^\alpha \partial_\alpha f) = \xi^\alpha \partial_\alpha \delta f$$



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The isometric operator $\mathcal{D}_{M,q}$ instead is quadratic and its differential $\ell_{M,q}$ is

$$\ell_{M,q}(f, \delta f) = \delta \mathcal{D}_{M,q}(f) = \delta(\delta_{ij} \partial_\alpha f^i \partial_\beta f^j) = 2\delta_{ij} \partial_\alpha f^i \partial_\beta \delta f^j$$



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Definition

We say that \mathcal{L}_r is *infinitesimally invertible* of defect $d \geq r$ and order s over some subset $\mathcal{A} \subset \Gamma^r F$ if there exist a family of *linear* PDOs $m_f : \Gamma^s G \rightarrow \Gamma_f^0(VF)$ of some order s , with $f \in \mathcal{A}$, satisfying the following properties:



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- 3 $\ell_r(m(f, \rho)) = \rho$ for every $f \in \Gamma^{r+d} F$ and $\rho \in \Gamma^{r+s} G$.



Linearization of a PDO

Example

The isometric operator $\mathcal{D}_{M,q} : C^1(M, \mathbb{R}^q) \rightarrow S_n^0(M)$ admits an infinitesimal inverse of defect 2 and order 0 over the space of free maps $F^2(M, \mathbb{R}^q)$.

Indeed we know that the linearized equation $\ell_{M,q}(f) = \delta g$ can be solved *algebraically* over the set of free maps. Let $\delta f_{f,\delta g}$ be the solution closest to the origin in some metric and set $m(f, \delta g) = \delta f_{f,\delta g}$. Clearly $\ell_{M,q}(m(f, \delta g)) = \delta g$.



The Implicit Function Theorem

Theorem (Nash, Gromov)

Let \mathcal{L}_r be a C^k PDO of order r admitting an infinitesimal inverse of order s and defect d over some subset $\mathcal{A} \subset \Gamma^r F$ and set $\hat{s} = \max(d, 2r + s) + s + 1$.

Then, for every $f_0 \in \mathcal{A} \cap \Gamma^\infty F$, there is a neighbourhood $\mathcal{U} \subset \Gamma^{\hat{s}} G$ of 0 such that, for every $\rho \in \mathcal{U} \cap \Gamma^{s'} G$ with $s' \geq \hat{s}$, the equation $\mathcal{L}_r(f) = \mathcal{L}_r(f_0) + \rho$ has a $C^{s'-s}$ solution.



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Corollary

Let \mathcal{L}_r a PDO infinitesimally invertible over $\mathcal{A} \subset \Gamma^r F$. Then the restriction of \mathcal{L}_r to $\mathcal{A} \cap \Gamma^\infty F$ is an open map.



Application: Nash Theorem

Theorem (Nash)

If $g_0 = \mathcal{D}_{M,q}(f_0)$ with $f_0 \in \text{Free}^\infty(M, \mathbb{R}^q)$, then the C^s metric $g_0 + g$, $s \geq 3$, can be realized by a C^s immersion f for every C^3 -small enough g .

Indeed in this particular case $r = 1$, $s = 0$ and $d = 2$, so that $\hat{s} = \max(d, 2r + s) + s + 1 = 3$.



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Indeed in this particular case $r = 1$, $s = 0$ and $d = 2$, so that $\hat{s} = \max(d, 2r + s) + s + 1 = 3$.

Hence the IFT theorem implies that, for every $f_0 \in \text{Free}^2(M, \mathbb{R}^q) \cap C^\infty(M, \mathbb{R}^q) = \text{Free}^\infty(M, \mathbb{R}^q)$, there is a neighbourhood $\mathcal{U} \subset \Gamma^3(\mathcal{S}_2^0 M)$ of 0 such that, for all $g \in \mathcal{U}$ of class $C^{s'}$, $s' \geq 3$, the equation $f^* e_q = g_0 + g$ has a solution of class $C^{s'}$.



The h-Principle



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A **formal** solution of \mathcal{R} is a C^0 section $\varphi : E \rightarrow J^r F$ st $\varphi(E) \subset \mathcal{R}$



Partial Differential Relations

Let $F \xrightarrow{\pi_F} E$ a C^∞ -fibration.

Definition

A *Partial Differential Relation* of order r is a subset $\mathcal{R} \subset J^r F$

A **formal** solution of \mathcal{R} is a C^0 section $\varphi : E \rightarrow J^r F$ st $\varphi(E) \subset \mathcal{R}$

A “true” solution of \mathcal{R} is a C^r section $f : E \rightarrow F$ st $j^r f(E) \subset \mathcal{R}$



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Sections of $\varphi : E \rightarrow J^r F$ such that $\varphi = j^r f$ are called **holonomic**

Obstructions to the existence of solutions of a PDR (in particular of a PDE) can be of *topological* or *analytical* origin. In the first case not even *formal* solutions exist. When formal solutions exist, analytical ones may or may not exist.



Partial Differential Relations

Example

Consider the case $E = \mathbb{R}^2 (x, y)$, $F = \mathbb{R}^2 \times \mathbb{R} (x, y, z)$ and $\mathcal{J}^1(\mathbb{R}^2, \mathbb{R}) (x, y, z, p_x, p_y)$.

Given a vector field $\xi = (\xi_x(x, y), \xi_y(x, y))$ on \mathbb{R}^2 , the 1st order PDE $L_\xi f = g$ is represented by the hypersurface

$$\mathcal{R} = \{\xi_x(x, y)p_x + \xi_y(x, y)p_y = g(x, y)\} \subset \mathcal{J}^1(\mathbb{R}^2, \mathbb{R})$$

If ξ is never zero, then there is no obstruction for its formal solvability for any $g \in C^0(\mathbb{R}^2)$, e.g. take

$$\varphi(x, y) = \left(x, y, z(x, y), g(x, y) \frac{\xi_x(x, y)}{\|\xi(x, y)\|}, g(x, y) \frac{\xi_y(x, y)}{\|\xi(x, y)\|} \right)$$

Depending on the topology of the integral trajectories of ξ , though, true solutions might not exist.

E.g. $\mathcal{R} = \{2yp_x + (1 - y^2)p_y = 1\}$ admits no holonomical C^1 section, namely there is no C^1 function f st

$$2y\partial_x f(x, y) + (1 - y^2)\partial_y f(x, y) = 1.$$



Prolongations of PDRs

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Given a PDR \mathcal{R} of order r , its 1-prolongation is

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\mathcal{R} is **stable** if $\mathcal{R}^{k+1} \rightarrow \mathcal{R}^k$ is an affine subbundle of $J^{k+1} F \rightarrow J^k F$ for all $k = 1, \dots$,



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Remark

Since the fibers of $\mathcal{R}^{k+1} \rightarrow \mathcal{R}^k$ are all contractible, if \mathcal{R} is stable then every section $\varphi : E \rightarrow \mathcal{R}$ lifts to a section $\varphi : E \rightarrow \mathcal{R}^k$ unique modulo homotopies.



Prolongations of the isometry PDR

Example

Consider the case $E = M^n (x^\alpha)$, $F = M^n \times \mathbb{R}^q (x^\alpha, f^a)$ and $J^1(M^n, \mathbb{R}^q) (x^\alpha, f^a, v_\alpha^a)$.

The isometric PDR I_g is the closed subset of $J^1(M^n, \mathbb{R}^q)$ of codimension s_n defined by the system

$$\delta_{ab} v_\alpha^a v_\beta^b = g_{\alpha\beta}(x).$$



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Its 1-prolongation I_g^1 is the closed subset of $J^2(M^n, \mathbb{R}^q)$ $(x^\alpha, f^a, v_\alpha^a, v_{\alpha\beta}^a)$ of codimension $(n+1)s_n$ defined by the system

$$\delta_{ab} v_\alpha^a v_\beta^b = g_{\alpha\beta}(x)$$

$$\delta_{ab} (v_{\alpha\mu}^a v_\beta^b + v_\alpha^a v_{\beta\mu}^b) = \partial_\mu g_{\alpha\beta}(x)$$



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$$\delta_{ab}(v_{\alpha\mu}^a v_\beta^b + v_\alpha^a v_{\beta\mu}^b) = \partial_\mu g_{\alpha\beta}(x)$$

equivalent to

$$\delta_{ab} v_\alpha^a v_\beta^b = g_{\alpha\beta}(x),$$

$$\delta_{ab} v_\alpha^a v_{\beta\gamma}^b = g_{\alpha\lambda}(x) \Gamma_{\beta\gamma}^\lambda(x), \quad \Gamma_{\beta\gamma}^\lambda = \frac{1}{2} g^{\lambda\mu} (\partial_\beta g_{\mu\gamma} + \partial_\gamma g_{\mu\beta} - \partial_\mu g_{\beta\gamma})$$



Prolongations of the isometry PDR

Example

Its second prolongation I_g^2 is the closed subset of $J^3(M^n, \mathbb{R}^q)$ $(x^\alpha, f^a, v_\alpha^a, v_{\alpha\beta}^a, v_{\alpha\beta\gamma}^a)$ of codimension s_{n+1} defined by the system

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$$\delta_{ab} \left(v_\alpha^a v_{\beta\gamma\mu}^b + v_{\alpha\mu}^a v_{\beta\gamma}^b \right) = \partial_\mu \left(g_{\alpha\lambda}(x) \Gamma_{\beta\gamma}^\lambda(x) \right)$$



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The last set of equations entails compatibility conditions

$$\delta_{ab} \left[v_{\alpha\gamma}^a v_{\beta\mu}^b - v_{\alpha\mu}^a v_{\beta\gamma}^b \right] = \partial_\mu \left[g_{\alpha\lambda}(x) \Gamma_{\beta\gamma}^\lambda(x) \right] - \partial_\beta \left[g_{\alpha\lambda}(x) \Gamma_{\mu\gamma}^\lambda(x) \right]$$

that are non-trivial for $n > 1$, so I_g^2 is not fibered over the whole I_g^1 (namely I_g is not stable!) unless $n = 1$.



The h-Principle

Definition

We say that a PDR \mathcal{R} of order r satisfies the h-Principle (for C^r solutions) if every C^0 section $\varphi : E \rightarrow \mathcal{R}$ is homotopic to a holonomic section $j^r f$ by a continuous homotopy of sections $\varphi_t : E \rightarrow \mathcal{R}$, $t \in [0, 1]$.



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We say that a PDR \mathcal{R} of order r satisfies the h-Principle for C^{r+k} solutions if every C^0 section $\varphi : E \rightarrow \mathcal{R}^k$ is homotopic to a holonomic section $j^{r+k} f$ by a continuous homotopy of sections $\varphi_t : E \rightarrow \mathcal{R}^k$, $t \in [0, 1]$.



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We say that a PDR \mathcal{R} of order r satisfies the h-Principle for C^∞ (C^{an}) solutions if \mathcal{R}^k is stable for some $k \geq 0$ and every C^0 section $\varphi : E \rightarrow \mathcal{R}^k$ is homotopic to a C^∞ (C^{an}) holonomic section $j^{r+k} f$ by a continuous homotopy of sections $\varphi_t : E \rightarrow \mathcal{R}^k$, $t \in [0, 1]$.



The h-Principle

The idea of the h-Principle is that, “if there is enough space”, *formal solutions* can be deformed into *true (holonomical) solutions*.

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Theorem (Grauert 1957)

Let G be a complex Lie group with a complex analytic subgroup H and consider a complex analytic fibration $F \rightarrow E$ with group structure G and fiber G/H .

Then, if V Stein, every continuous section of $F \rightarrow E$ can be homotoped to a holomorphic one.

In Gromov's language, the Cauchy-Riemann PDR satisfies the C^{an} h-principle (note that this (closed) PDR is *stable*).



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Theorem (Hirsh 1959, 1961)

Let M, N be two smooth manifolds. Then every continuous section of the bundle $GL(TM, TN) \rightarrow M$ can be homotoped to the 1-jet of an immersion $M \rightarrow N$ in the following two cases:

- *Extra dimension*: $\dim N > \dim M$;
- *Critical Dimension*: $\dim N = \dim M$ and N is open.

In Gromov's language, the immersion PDR satisfies the C^∞ h-principle (note that this PDR is open and, therefore, *stable*).



The h-Principle

The idea of the h-Principle is that, “if there is enough space”, *formal solutions* can be deformed into *true (holonomical) solutions*.

This idea arose out of a series of several discoveries in immersions theory:

Theorem (Nash 1954, Kuiper 1955)

Every C^1 immersion $M \rightarrow \mathbb{R}^q$ admits a C^1 homotopy of immersions to an isometric immersion.

In Gromov's language, the immersion PDR satisfies the C^1 h-Principle (note that this PDR is not stable so these solutions cannot be made more regular).



Techniques to prove the h-Principle

The last two theorems provide two of the main techniques used by Gromov to prove the validity of the h-Principle for a PDR:

- *Sheaves technique*, based on the work of Smale and Hirsch;



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- *Sheaves technique*, based on the work of Smale and Hirsch;
- *Convex integration*, based on the work of Nash and Kuiper, especially useful in case of closed PDR;
- *Removal of Singularities technique*, developed by Gromov and Eliashberg, especially useful in the complex analytical or algebraic setting.



h-Principle & Free maps

Theorem

Let M^n be a smooth manifold and $\mathcal{F} \subset J^2(M, \mathbb{R}^q)$ the free maps PDR – namely in coordinates $(x^\alpha, f^a, v_\alpha^a, v_{\alpha\beta}^a)$ every fiber of \mathcal{F} is defined as $\text{rk} \begin{pmatrix} v_\alpha^a \\ v_{\alpha\beta}^a \end{pmatrix} = s_n$.



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Then every continuous section of $\mathcal{F} \rightarrow M$ can be homotoped to the 2-jet of a free map $M \rightarrow \mathbb{R}^q$ in the following two cases:

- Extra dimension: $q > n + s_n$;
- Critical Dimension: $q = n + s_n$ and M is open.



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Then every continuous section of $\mathcal{F} \rightarrow M$ can be homotoped to the 2-jet of a free map $M \rightarrow \mathbb{R}^q$ in the following two cases:

- Extra dimension: $q > n + s_n$;
- Critical Dimension: $q = n + s_n$ and M is open.

Corollary

If M is a stably parallelizable n -manifold (e.g. any orientable hypersurface of \mathbb{R}^{n+1}), it admits a free map into \mathbb{R}^{n+s_n+1} .



h-Principle & Free maps

Open Question

Do free maps of closed manifolds M , $\dim M \geq 2$, satisfy the h-Principle for $n + s_n$?

Does every parallelizable manifold (in particular the n -torus) admit a free map into \mathbb{R}^{n+s_n} ?



h-Principle for C^k isometries, $k \geq 3$.

Although the isometries PDR I_g is not stable for any metric g , the PDR $(\mathcal{F} \cap I_g^1)^1$ is stable for all metrics g .

Theorem

Let (M^n, g) be a C^k Riemannian manifold, $k \geq 5$. Then free isometric C^k immersions $M \rightarrow \mathbb{R}^q$ satisfy the h-Principle for $q \geq 5n+1$.



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Since $\mathcal{F} \rightarrow M$ admits always a section for $q \geq 2n + s_n$, this is equivalent to

Theorem

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